Comparative Analysis of Solution Methods for Delay Differential Equations in Haematology

Gergana Bencheva

Institute for Parallel Processing

Bulgarian Academy of Sciences

gery@parallel.bas.bg

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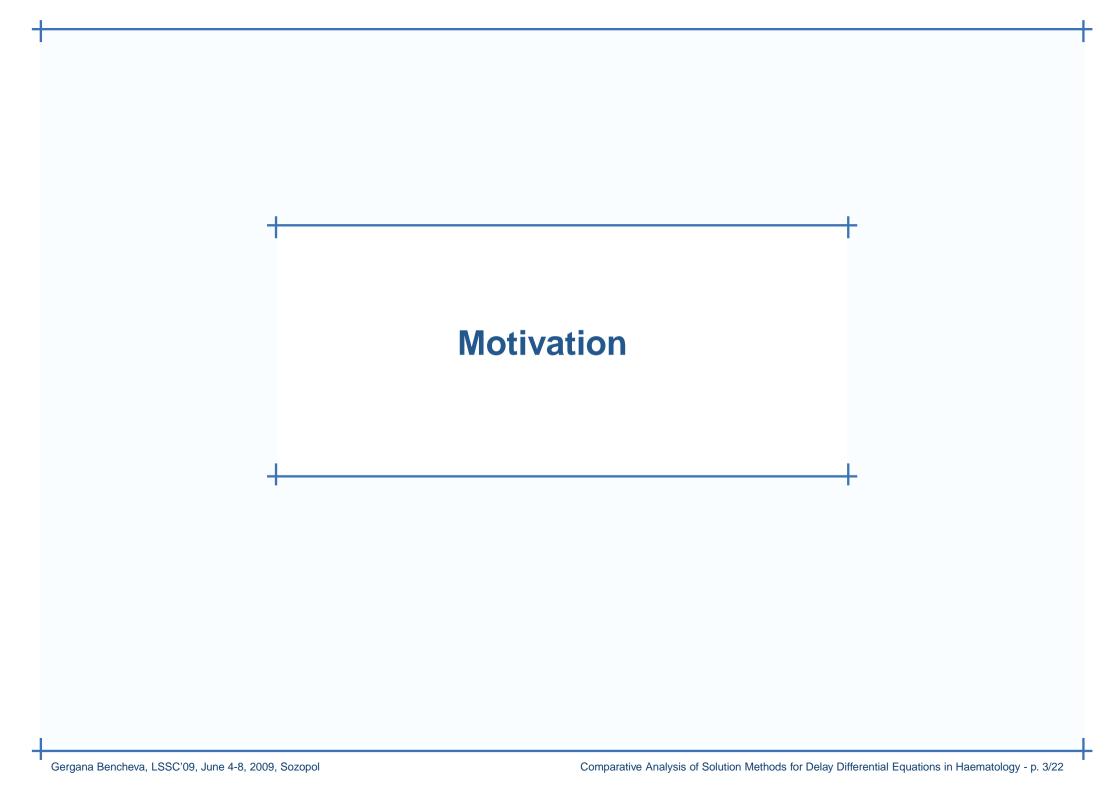
Motivation

Delay differential equations

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- Numerical tests
- Further steps



Blood cells production and regulation

Motivation

- Haematopoiesis
- Differentiation stages
- Need for simulation

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Haematopoietic pluripotent stem cells (HSCs) in bone marrow give birth to the three blood cell types.

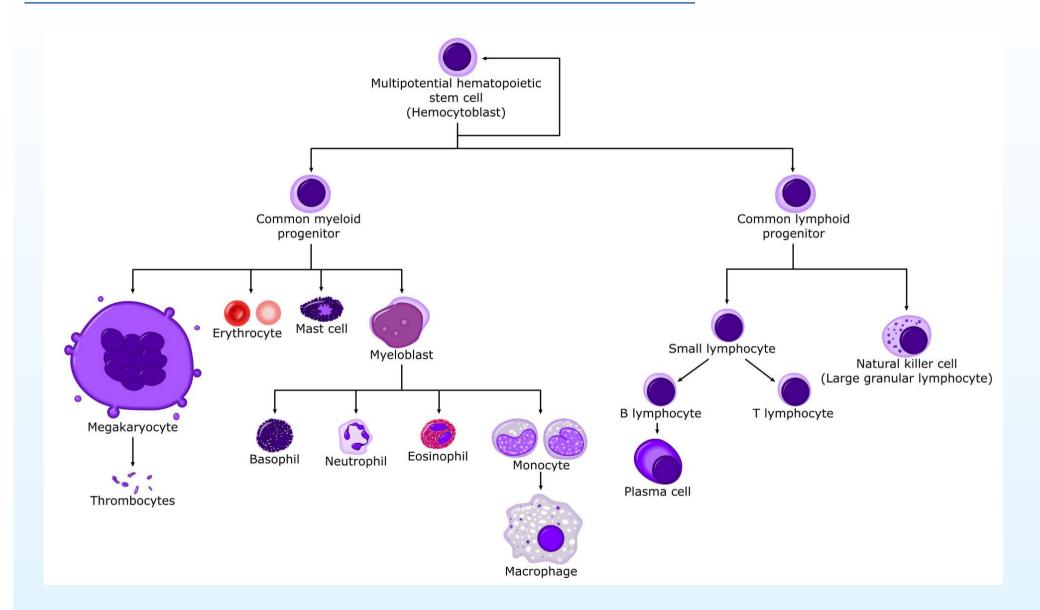
Growth factors or Colony Stimulating Factors (CSF) – specific proteins that stimulate the production and maturation of each blood cell type.

Blast cells – blood cells that have not yet matured.

| Blood cell type | Function | Growth factors |
|-----------------|-----------------------------|----------------|
| Erythrocyte | Transport oxygen to tissues | Erythropoietin |
| Leukocyte | Fight infections | G-CSF, M-CSF, |
| | | GM-CSF, |
| | | Interleukins |
| Thrombocyte | Control bleeding | Thrombopoietin |

Various hematological diseases (including leukemia) are characterized by abnormal production of particular blood cells (matured or blast).

Differentiation stages in haematopoiesis



Need for computer simulation

The approach "trial-error" is not recommended for dealing with questions related to understanding and predicting of human physiological processes in health and disease.

Development of software tools for real-time data-driven simulation of haematopoiesis will give possibility to

- understand better the blood cells production and regulation processes;
- design nature experiments for validation of hypotheses;
- predict the effect of various treatment options for patients with specific hematological diseases;

Current step: comparison of some already existing solvers

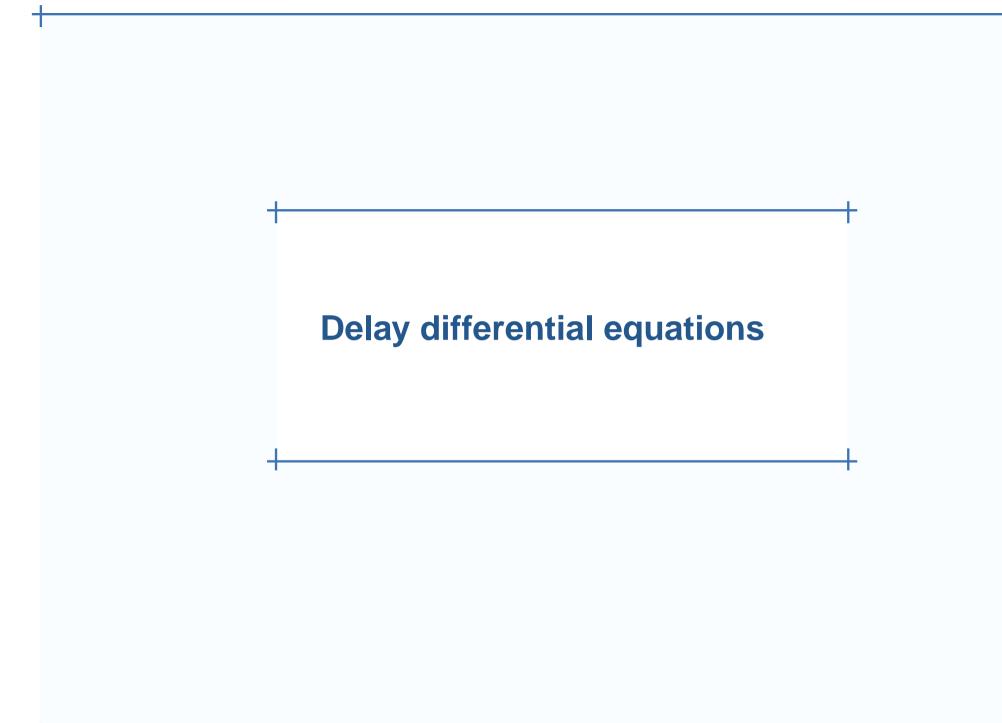
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Mathematical model

Motivation

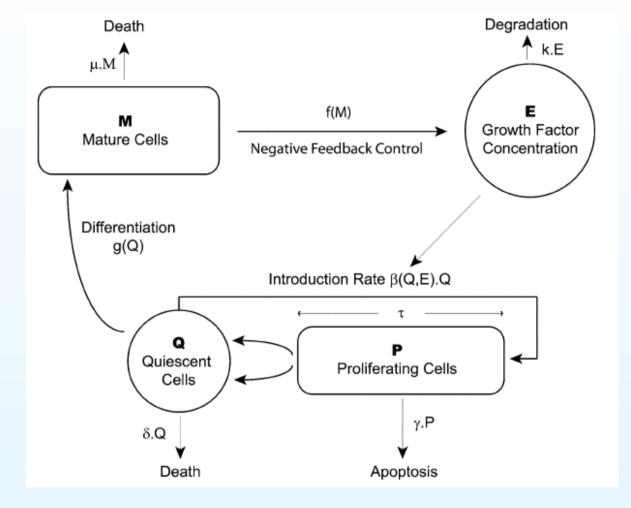
Delay differential equations

- Mathematical model
- System of ODEs with delay

Solution methods

Numerical tests

Further steps



[ACR] M. Adimy, F. Crauste, S. Ruan, Modelling Hematopoiesis Mediated by Growth Factors with Applications to Periodic Hematological Diseases, Bulletin of Mathematical Biology, 68 (8), (2006), 2321-2351.

System of ODEs with delay

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- System of ODEs with delay

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$$\begin{cases} \frac{dQ}{dt} &= -\delta Q(t) - g(Q(t)) - \beta(Q(t), E(t)) Q(t) \\ + 2e^{-\gamma \tau} \beta(Q(t - \tau), E(t - \tau)) Q(t - \tau) \end{cases}$$

$$\begin{cases} \frac{dM}{dt} &= -\mu M(t) + g(Q(t)) \\ \frac{dE}{dt} &= -kE(t) + f(M(t)) \end{cases}$$

$$Q(t) = Q_0(t), M(t) = M_0(t), E(t) = E_0(t), t \in [-\tau, 0]$$

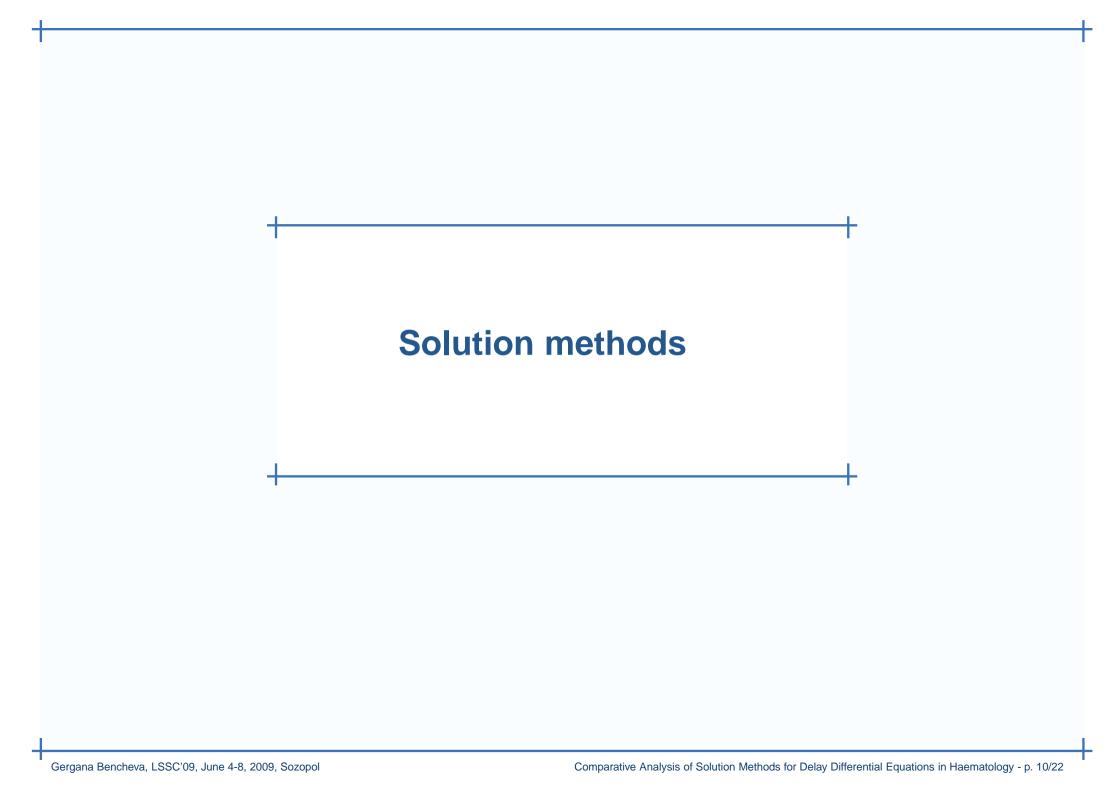
Delay τ corresponds to the cell cycle duration.

$$Q(t) \ge 0, M(t) \ge 0, E(t) \ge 0, k > 0, \mu > 0$$

Existence of nontrivial positive steady-state is ensured by:

$$0 < \delta + g'(0) < \beta \left(0, \frac{f(0)}{k}\right) \text{ and}$$

$$0 \le \tau < \tau_{max} := \frac{1}{\gamma} \ln \left(\frac{2\beta \left(0, \frac{f(0)}{k}\right)}{\delta + g'(0) + \beta \left(0, \frac{f(0)}{k}\right)}\right)$$



What is XPPAUT?

Motivation

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• What is XPPAUT?

The methods

Numerical tests

Further steps

"A tool for simulating, animating and analyzing dynamical systems." (G. B. Ermentrout)

Some of the features:

- brings together useful algorithms for solving various types of equations, including DDEs;
- contains the code for bifurcation program AUTO;
- provides means for visualisation of the solution;
- portable on various systems and its building requires the standard C compiler and Xlib.

B. Ermentrout, Simulating, analyzing and animating dynamical systems: a guide to XPPAUT for researchers and students, SIAM, 2002

http://www.math.pitt.edu/~bard/xpp/xpp.html

The methods

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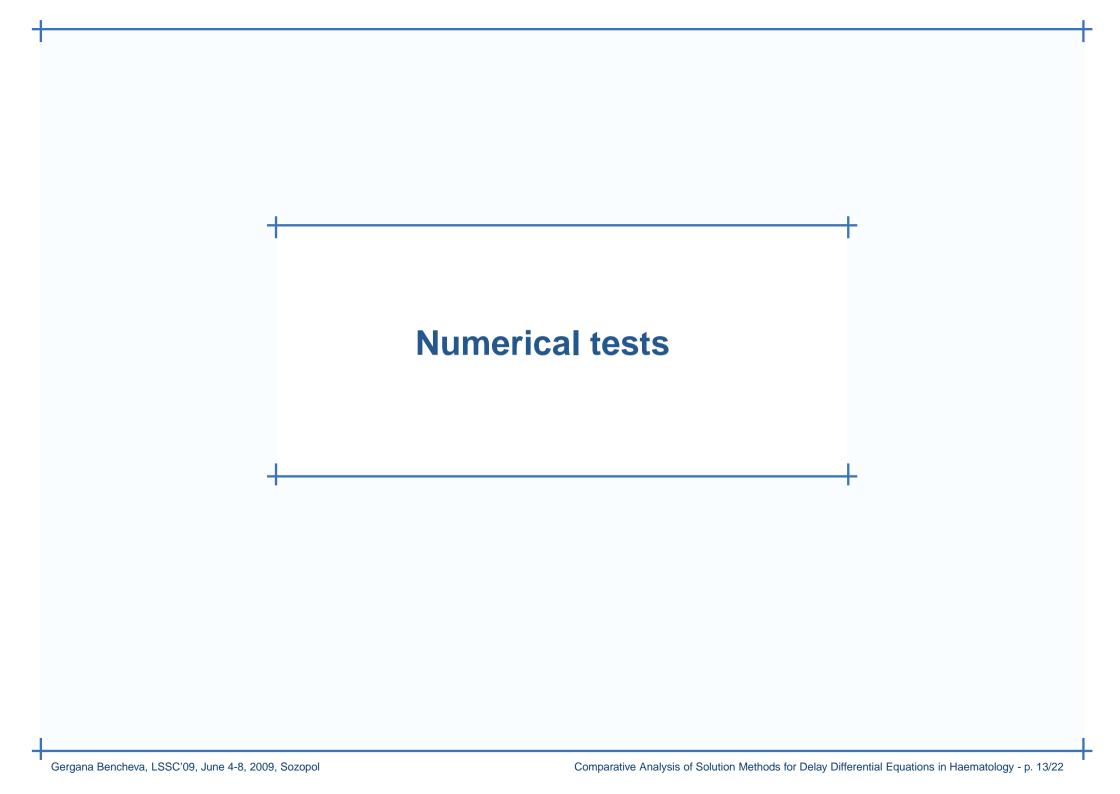
| | Expl. | Impl. | FS | AS | Stiff |
|------------------------|-------|-------|----|----|-------|
| Runge Kutta (RK) | + | | + | | |
| Adams (AD) | + | | + | | |
| Dormand-Prince 5 (DP5) | + | | | + | |
| Backward Euler (BE) | | + | + | | |
| CVODE (CV) | | + | | + | + |
| Rosenbrock (RB2) | | + | | + | + |

CVODE is based on C-version of LSODE, written by S. D. Cohen and A.C. Hindmarsh, LLNL.

Rosenbrock is based on Matlab version of the two step Rosenbrock algorithms.

Delay equations are solved by storing previous data and using cubic polynomial interpolation to obtain the delayed value.

E. Hairer, (S.P. Norsett), G. Wanner, Solving ordinary differential equations I, II, Springer Ser. in Comp. Math., Springer, 2000 (part I), 2002 (part II)



Model parameters for erythropoiesis

Motivation

Delay differential equations

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- Model parameters
- Computing time
- Comparison of solutions

| $\beta(E) = \beta_0 \frac{E}{1+E},$ | $\beta_0 > 0$ | $	au \in [0, 	au_{max})$ |
|-------------------------------------|-----------------|----------------------------|
| g(Q) = GQ, | G > 0 | $\tau_{max} = 2.99 \ days$ |
| $f(M) = \frac{a}{1 + KM^r},$ | a, K > 0, r > 0 | |

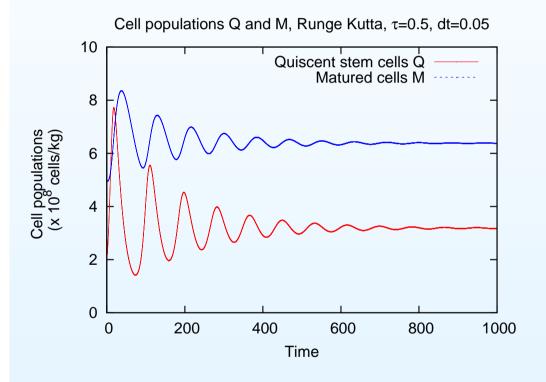
| Parameter | Value in [ACR] | Range (day^{-1}) | | |
|-----------|-------------------|--------------------|--|--|
| δ | $0.01 \ day^{-1}$ | 0 - 0.09 | | |
| G | $0.04 \ day^{-1}$ | 0 - 0.09 | | |
| eta_0 | $0.5 \ day^{-1}$ | 0.08 - 2.24 | | |
| γ | $0.2 \ day^{-1}$ | 0 - 0.9 | | |
| μ | $0.02 \ day^{-1}$ | 0.001 - 0.1 | | |
| k | $2.8 \ day^{-1}$ | | | |
| a | 6570 | | | |
| K | 0.0382 | | | |
| r | 7 | | | |

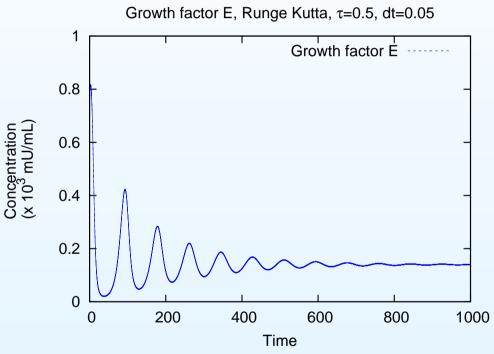
Computing time

| | $\tau = 0.5$ | | | au = 1.4 | | | $\tau = 2.9$ | | |
|--|--------------|------|------|----------|------|------|--------------|------|------|
| $\begin{tabular}{ c c c c c c c c c c c c c c c c c c c$ | 0.2 | 0.1 | 0.05 | 0.2 | 0.1 | 0.05 | 0.2 | 0.1 | 0.05 |
| RK | 0.05 | 0.09 | 0.2 | 0.04 | 0.09 | 0.18 | 0.04 | 0.1 | 0.19 |
| AD | 0.02 | 0.04 | 0.1 | 0.03 | 0.05 | 0.1 | 0.02 | 0.05 | 0.1 |
| BE | 0.13 | 0.25 | 0.46 | 0.15 | 0.30 | 0.56 | 0.15 | 0.26 | 0.49 |
| DP5 $(1.e - 6)$ | 0.09 | 0.17 | 0.34 | 0.08 | 0.18 | 0.35 | 0.09 | 0.17 | 0.34 |
| DP5 $(1.e - 9)$ | 0.12 | 0.19 | 0.35 | 0.17 | 0.25 | 0.34 | 0.13 | 0.18 | 0.34 |
| CV (1.e - 6) | 0.12 | 0.1 | 0.07 | 0.28 | 0.29 | 0.14 | 0.07 | 0.03 | 0.02 |
| CV (1.e - 9) | 0.62 | 1.0 | 1.66 | 0.75 | 1.28 | 1.96 | 0.58 | 0.67 | 0.96 |
| RB2 $(1.e - 6)$ | 0.17 | 0.34 | 0.65 | 0.17 | 0.32 | 0.65 | 0.17 | 0.32 | 0.64 |
| RB2 $(1.e - 9)$ | 0.49 | 0.57 | 8.0 | 1.17 | 1.18 | 1.27 | 0.59 | 0.53 | 0.78 |

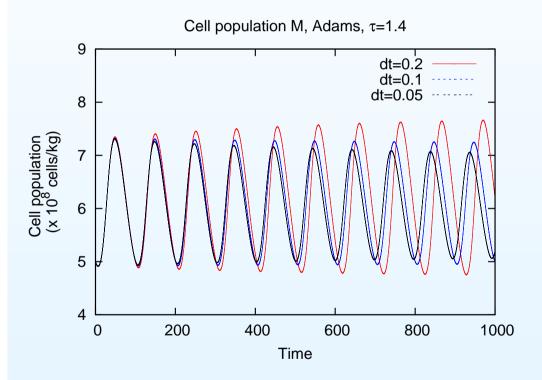
dt – step size for the fixed step integrators and output step for the others.

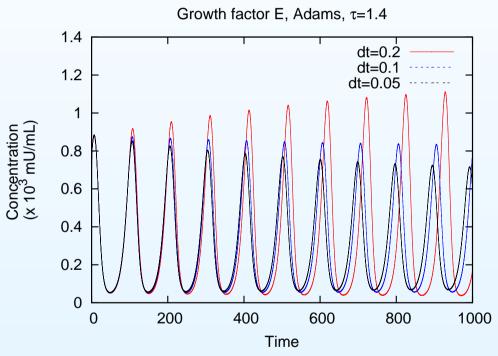
Solution with Runge Kutta for $\tau=0.5$



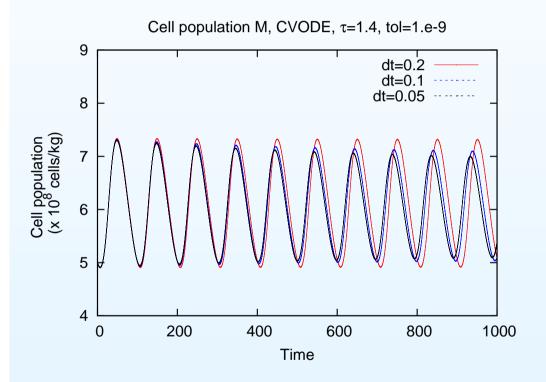


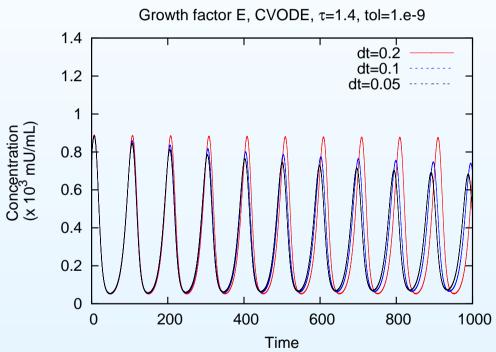
Solution with Adams for $\tau=1.4$



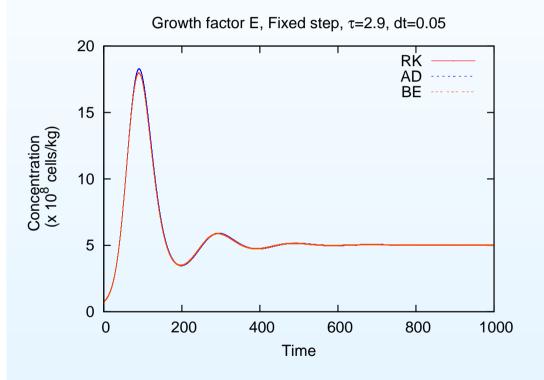


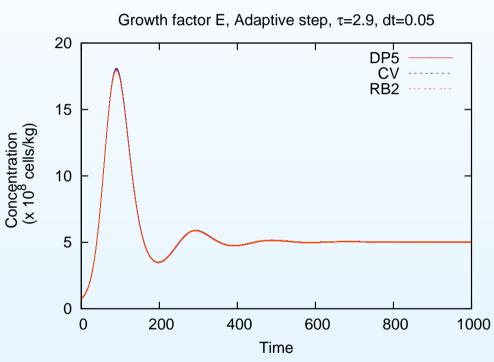
Solution with CVODE for $\tau=1.4, tol=1.e-9$



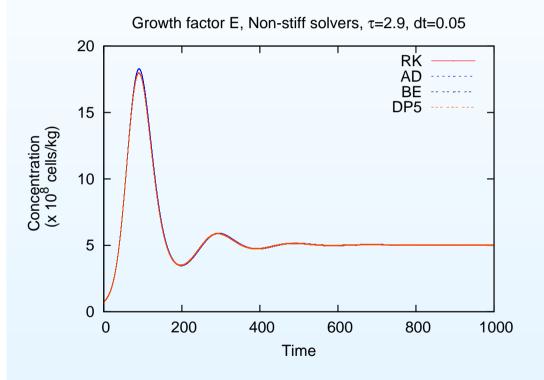


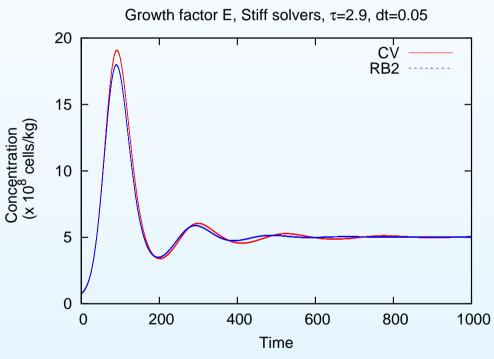
Comparison fixed/adaptive step methods for $\tau=2.9$

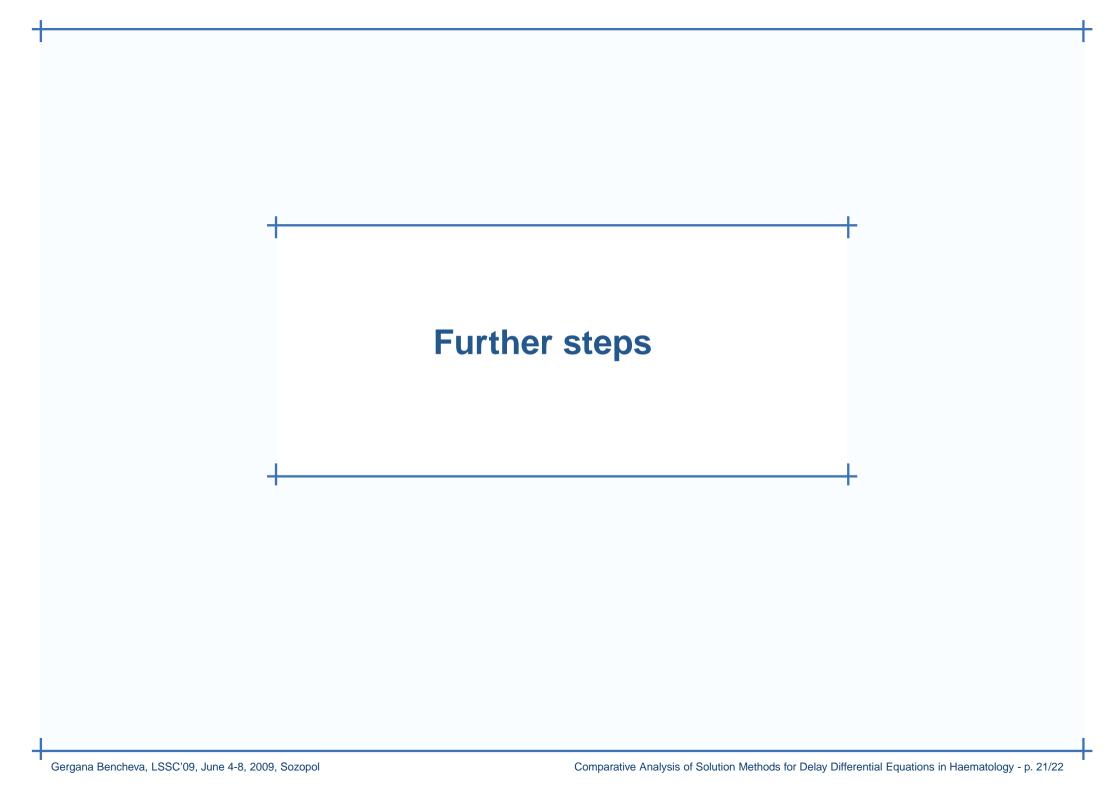




Comparison nonstiff/stiff solvers for $\tau = 2.9$







Further steps

Calibration of the model and software tools for:

- leukocytes (each of the 7 types) and thrombocytes on the base of model data, e.g. taken from papers and experiments in vitro;
- each of the three blood cell types on the base of real data from clinical practice, i.e. on the base of patient specific data taken in vivo.

These include identification of parameters and sensitivity analysis as intermediate steps.

Thank you for your attention!

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